Introduction to Consensus Algorithms

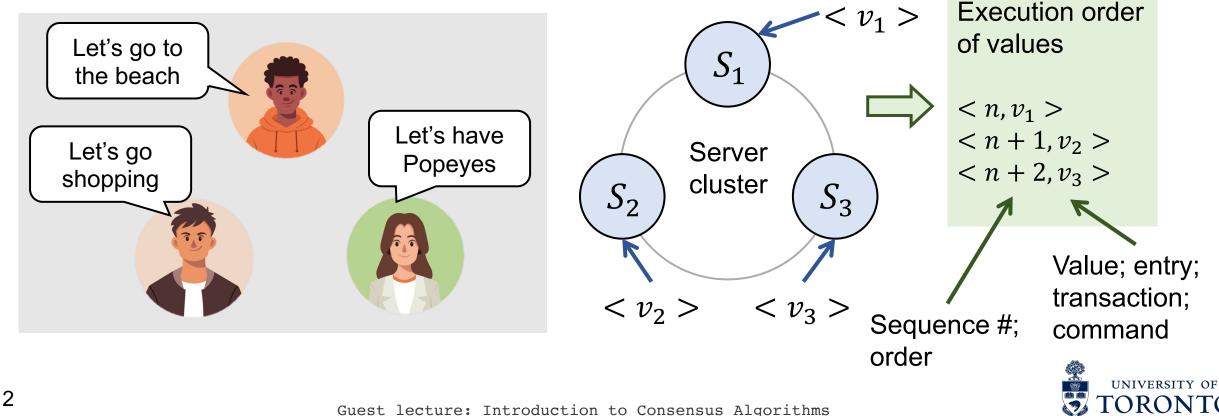
ECE1779 Guest Lecture

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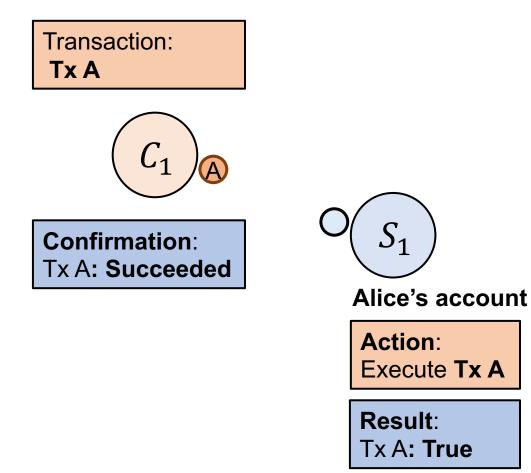
ECE, University of Toronto

What is a consensus algorithm?

- ``Consensus" means ``a general agreement"
- In distributed systems, consensus algorithms coordinate server actions to reach agreement on committing values/executing commands



Why do we need consensus algorithms?



- Clients invoke a service by sending a request to server
- Server replies to the client with the result of invocation

Question: What if the server fails?

Does this model suffice to build safety-critical applications?



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Failures are inevitable and ubiquitous

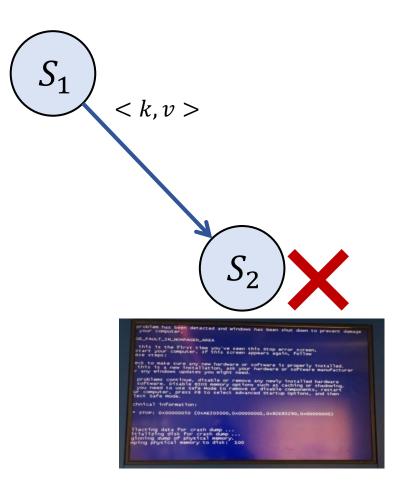


System Design Goal: We need a system that can tolerate failures; i.e., a system that can function correctly when failures take place

Credit: bennio. via Reddit

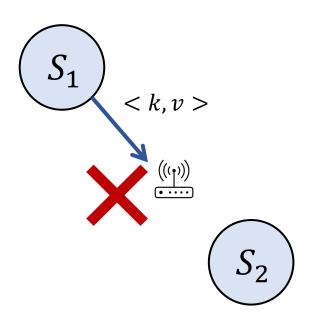


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Crash failures

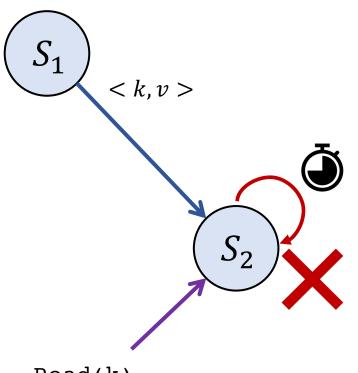




Crash failures

Omission failures





Read(k) Return \rightarrow **null** Crash failures

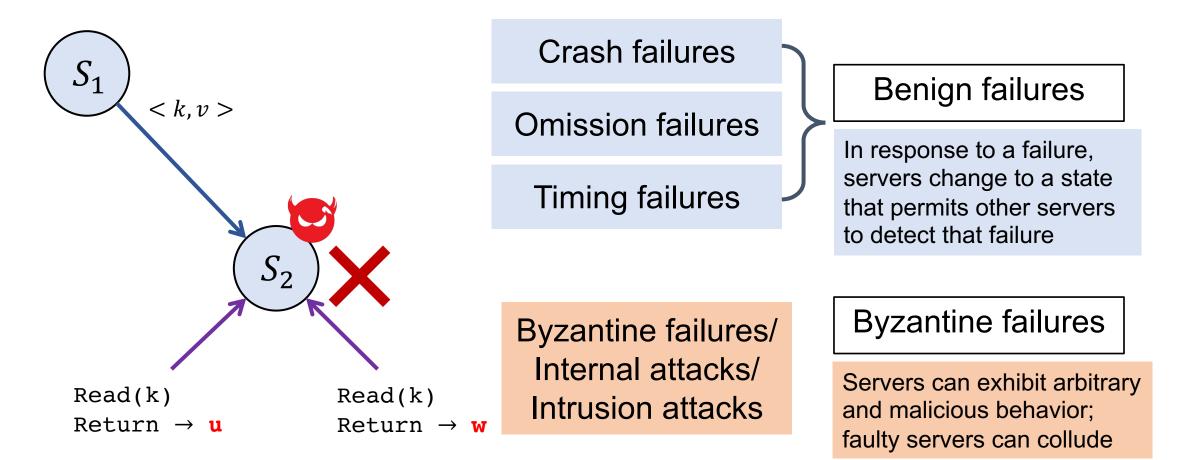
Omission failures

Timing failures

Benign failures

In response to a failure, servers change to a state that permits other servers to detect that failure







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Applying fault tolerance with redundancy

 Fault tolerance makes the system operate correctly even if some servers become faulty

Q: Recall how does the disk system tolerate failures?

A: RAID (Redundant Array of Independent Disks)

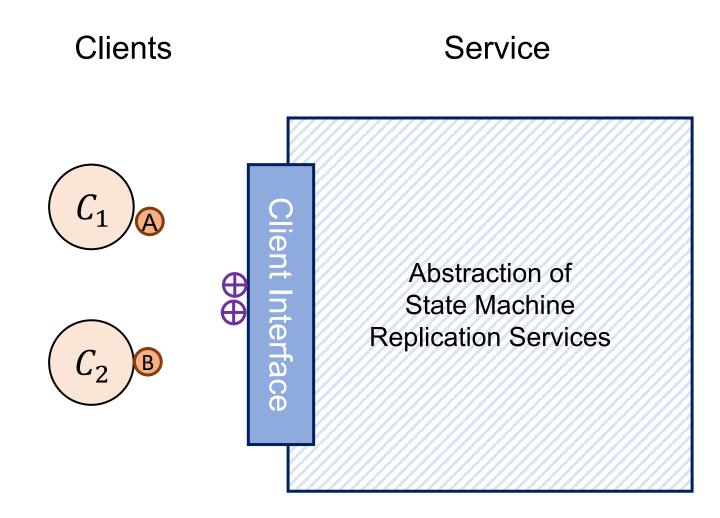
- Redundancy in distributed systems: a collection of independent servers
 - Normally, a set of servers operate as a logically single server
 - If some servers are down, the remaining ones can still perform the task

Question

How can we make a set of servers operate like a logically single server? I.e., how can we manage the consistency among servers?



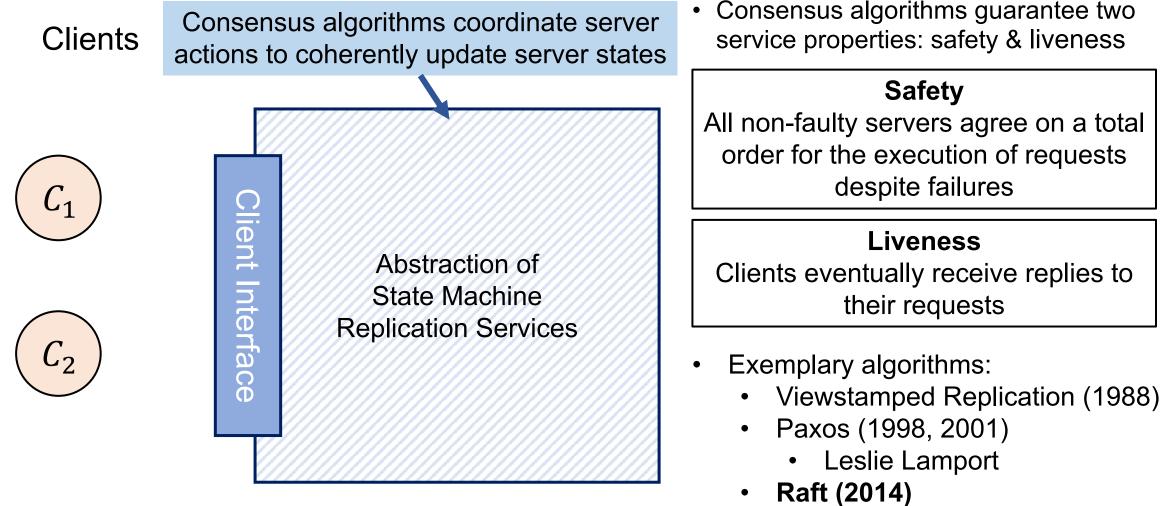
State machine replication (SMR)



- SMR is a replication service where a set of servers compute identical copies of the same state
- SMR provides an abstraction of its replication service with a client interface
- Clients treat SMR services as a black box
 - Send requests to the provided interface
 - Wait for replies to confirm their requests



Consensus algorithms in SMR





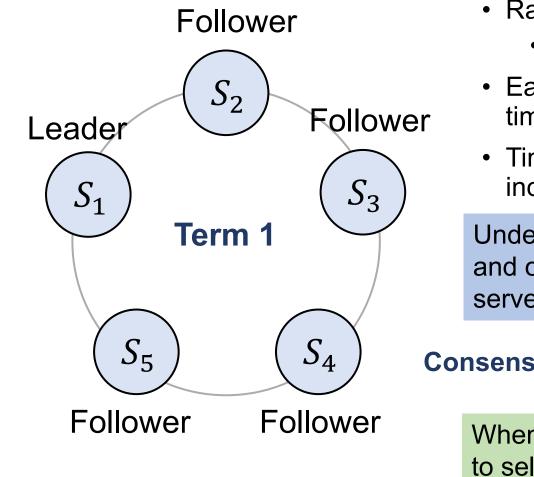
The Raft consensus algorithm



- Published by Diego Ongaro et al. (from Stanford) and received Best Paper Award from <u>2014 USENIX Annual Technical Conference</u>
- Raft is a leader-based consensus algorithm
 - More understandable than Paxos
 - Uses a designated server as a leader
 - Tolerates benign failures
 - E.g., server crash, packet loss, duplication, and reordering
- It has had a great impact on a wide range of applications:
 - File systems: PolarFS [VLDB'18]
 - Databases: CockroachDB^{[Sigmod'20],} Etcd, and MongoDB (a Raft's variant)
 - Cloud computing: Docker (cluster state), Kubernetes (replication)



Raft basics 1: server states and terms



- Raft has two major operating stages
 - Replication and leader election
- Each server is in one of three states at any given time: **leader**, **follower**, **candidate**
- Time is divided into **terms** (logical time), which increase monotonically

Under normal operation, there is **one leader** in a term and other servers run as followers; the leader coordinates server actions to conduct consensus

Consensus in replication

Consensus in leader election

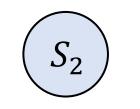
When a leader fails, the other servers start leader election to select a new leader from the remaining servers



Raft basics 2: timers and heartbeats

Leader Term 1 S_1

Follower



• Each follower uses a timer to monitor the health of the leader

- Timer keeps counting down until follower receives a message from leader
- Otherwise, timer expires; follower becomes a candidate and starts a leader election campaign
- Leader sends periodic heartbeats to reset followers' timers
 - Interval of heartbeats << Timer timeouts (e.g., 100 ms) (e.g., 1-2 s)



Timer

Replication in Raft (Phase I: ordering)

Service Clients *S*₂ S_3 S_1 C_2 B S_5 S_4

In term 1 (leader: S_1)		
Ordering	Commit	
$S_1: \bigcirc \bigcirc$	<i>S</i> ₁ :	
<i>S</i> ₂ :	<i>S</i> ₂ :	
<i>S</i> ₃ :	<i>S</i> ₃ :	
<i>S</i> ₄ :	$S_1:$ $S_2:$ $S_3:$ $S_4:$ $S_5:$	
$S_1: A B$ $S_2:$ $S_3:$ $S_4:$ $S_5:$	<i>S</i> ₅ :	

• Clients send requests to leader



Replication in Raft (Phase I: ordering)

Service Clients S_2 \mathcal{L}_1 S_3 S_1 C_2 S_5 S_4

In term 1 (leader: S_1)		
Ordering	Commit	
$S_1: \bigcirc \mathbb{B}$	<i>S</i> ₁ :	
$S_2: A$	S_2 :	
$S_3: A$ $S_4: A$	$S_1:$ $S_2:$ $S_3:$ $S_4:$ $S_5:$	
S_5 :	<i>S</i> ₅ :	

- Clients send requests to leader
- Leader assigns a sequence # to client request
 - E.g., < *n*, *a* >; < *n* + 1, *b* >



Replication in Raft (Phase II: committing)

Clients Service S_2 \oplus S_3 S_1 Ð C_2 \oplus Œ S_4 S_5

In term 1 (leader: S_1)	
Ordering	Commit
$S_1: \bigcirc \mathbb{B}$ $S_2: \bigcirc$	$S_1: \bigcirc S_2:$
$S_2: A$	<i>S</i> ₂ :
S_3 :	$S_3:$ $S_4:$ $S_5:$
S_4 :	<i>S</i> ₄ :
$S_5: \bigwedge$	<i>S</i> ₅ :

- Clients send requests to leader
- Leader assigns a sequence # to client request
 - E.g., < n, a >; < n + 1, b >
- Leader commits the value if a majority of replies can be collected



Replication in Raft (Phase II: committing)

Clients Service S_2 S_3 S_1 C_2 S_5 S_4

In term 1 (leader: S_1)	
Ordering	Commit
$S_1: \bigcirc \mathbb{B}$	$S_1: \bigcirc$
S_2 :	S_2 : \bigwedge
S_3 :	$S_3: \bigwedge$ $S_4: \bigwedge$
S_4 :	S_4 :
$S_5: \mathbf{A}$	S_5 : \textcircled{A}

- Clients send requests to leader
- Leader assigns a sequence # to client request
 - E.g., < n, a >; < n + 1, b >
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Summary of Raft's replication

- Strong leadership:
 - Log entries flow only from the leader to followers
 - Follower must synchronize its log according to leader's log
- Quorum replication:
 - In a system consisting of n = 2f + 1 servers, an action can be agreed upon by f + 1 servers (majority)
 - E.g., in a 5-server system, 3 servers form a majority
 - A minority (≤ f) of slow servers do not impact overall replication performance



Impact of failures

 Under a correct leader, as long as a majority of servers are correct, the system can operate correctly

- Leader is the most crucial role
 - It interacts with clients and coordinates consensus with other servers
 - Other servers synchronize with the leader

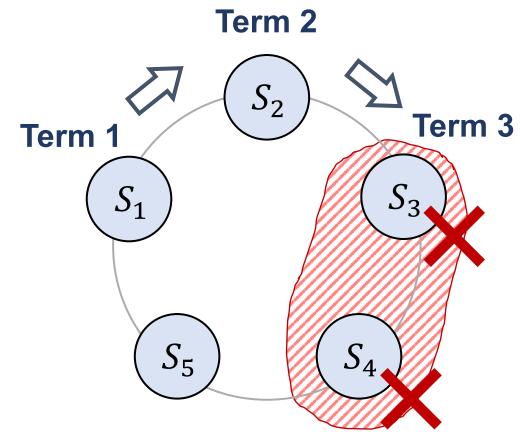
A new leader should have

- the highest term value
- the most up-to-date log

Make sure the system **never falls back** to a previous state; i.e., not loosing log entries when leadership changes



Solution 1: Passive leadership rotation



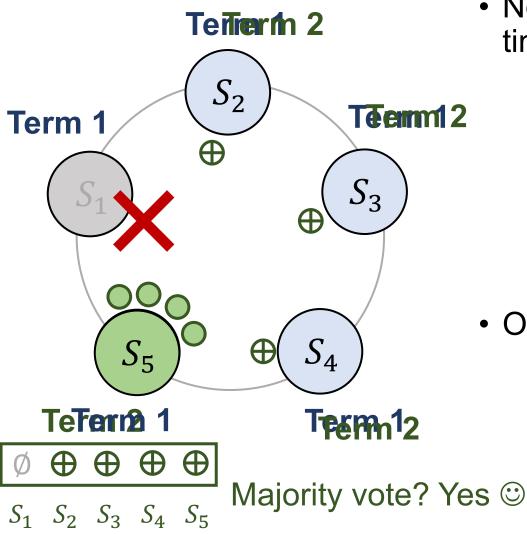
[Viewstamped Replication]

- All servers follow a pre-defined leader schedule to rotate leadership
 - Leader = Term *mod* # of servers
 - I.e., leadership is assigned to $S_1 \rightarrow S_2 \rightarrow S_3 \rightarrow S_4 \rightarrow S_5 \rightarrow S_1 \rightarrow \cdots$
- Pros:
 - Simple; easy to understand and implement
- Cons:
 - Cannot avoid already crashed servers
 - Cannot avoid slow servers

Can we do better?



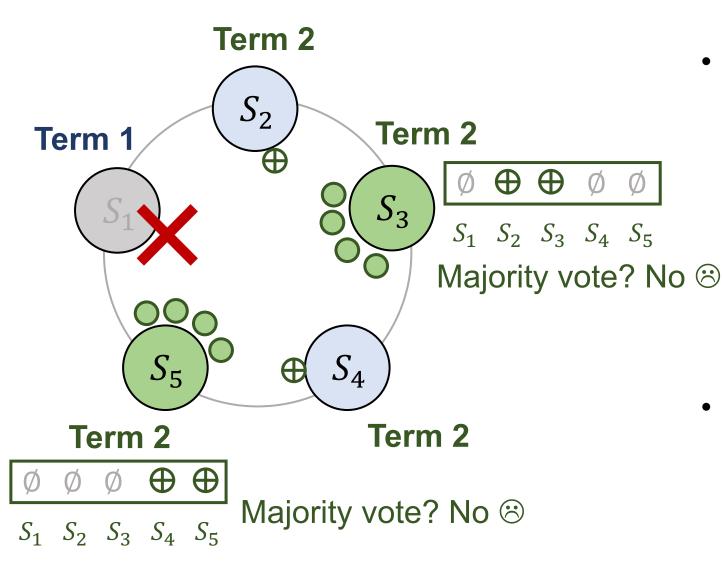
Raft's solution: Active leader election



- No leader schedule; whoever triggers a timeout campaigns for leadership
 - Transitions to candidate
 - Increments its term
 - Sends out messages to request votes from other servers in the form of <term, lastLogIndex, lastLogTerm>
 - Votes for itself
- Other servers vote for the candidate if
 - Candidate's term >= receiver's term
 - Receiver has not voted in this term
 - Candidate's log is at least as up-to-date as receiver's log



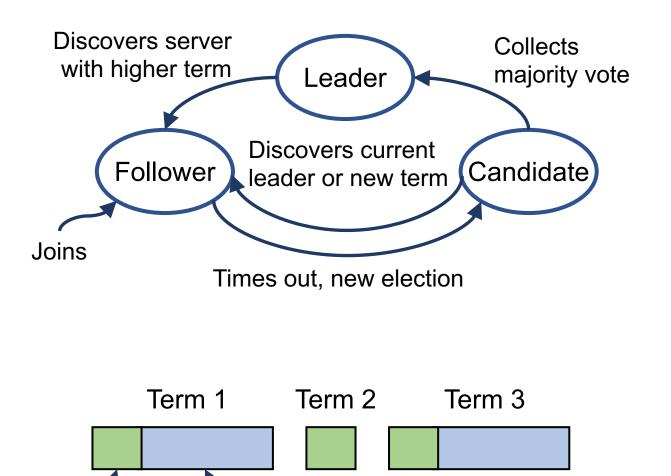
A problem: split votes in leader election



- Servers S₃ and S₅ both trigger timeouts and transition to candidate state
 - S_2 votes for S_3 and will not vote for S_5
 - Similarly, S_4 votes for S_5 and will not vote for S_3
 - No candidate can collect majority vote
- Raft's solution:
 - Randomized timers
 - Waiting for new elections



Raft's server state transition



Replication

- Only a qualified server will be elected as a new leader
 - Crashed servers will not be assigned with leader duty
 - Slow servers will not be elected
- At most one leader can be elected as a leader in a given term
 - Elected leader conducts consensus in its term
 - Some terms may result in no leader being elected



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Time

Leader election

Summary

- Raft operates in a succession of **terms** with two major components
 - Leader election: the consensus to agree on a leader
 - Replication: the consensus to agree on client requests
- Raft is fast and efficient
 - It can tolerate up to f + 1 benign failures among a total of 2f + 1 servers
 - Under normal operation, it can achieve consensus by collecting replies from a majority of servers (f + 1)
 - Its leader election mechanism allows servers to proactively campaign for leadership, thereby avoiding unqualified servers to be elected



Additional resources

- This lecture does not cover all the details of Raft
 - Check out the full paper at: https://raft.github.io/raft.pdf
 - Raft's visualization: https://raft.github.io/
- Solving Raft's split vote problem:
 - G. Zhang and H. -A. Jacobsen, "ESCAPE to Precaution against Leader Failures," *2022 IEEE 42nd International Conference on Distributed Computing Systems (ICDCS)*. <u>https://ieeexplore.ieee.org/document/9912172</u>





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Learn more about consensus algorithms at: <u>https://gengruizhang.github.io/</u>

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